

THE CONDENSER PROBLEM

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The condenser theorem in classical potential theory is studied within the framework of Markov processes and probabilistic potential theory. The condenser charge is expressed in terms of successive balayages of a capacitary measure.

1. Introduction. In classical potential theory on \mathbb{R}^d with $d \geq 3$ (or, more generally, in theory of Dirichlet spaces) the "condenser theorem" states the following (see, for example, page 380 of [5]). Let G_0 and G_1 be open sets with disjoint closures \bar{G}_0 and \bar{G}_1 and assume that \bar{G}_1 is compact. Then there exists a potential p of a signed measure ν such that:

- (i) $0 \leq p \leq 1$ a.e. on \mathbb{R}^d .
- (ii) $p = 0$ a.e. on G_0 and $p = 1$ a.e. on G_1 .
- (iii) The support of ν^+ is contained in \bar{G}_1 and the support of ν^- is contained in \bar{G}_0 .

From (i) and (ii) one would guess that $p(x)$ is just the probability that a Brownian motion starting at x hits G_1 before G_0 , and consequently (i) and (ii) hold everywhere rather than almost everywhere. With this motivation it is very easy to give a probabilistic proof of the condenser theorem and to study the condenser problem within the framework of Markov processes. This note is devoted to such a study. In order to keep things simple we shall consider only Hunt processes with a locally compact metrizable state space E . (The expert should have no difficulty extending our results to the "right" processes.) Our method yields some interesting by-products. For example, it turns out that ν^+ is the capacitary measure, μ , of G_1 for the process killed when it first hits G_0 and that ν^- is the balayage of $\nu^+ = \mu$ on G_0 . Moreover, we obtain an explicit formula (3.2) for μ in terms of the successive balayages on G_0 and G_1 of the capacitary measure π of G_1 for the entire process.

2. Let X be a Hunt process with state space E as in [2]. We refer the reader to [2] for all unexplained notation and terminology. Let D and B be nearly Borel sets with disjoint closures. We assume that D is transient in the sense that if $L = L_D = \sup \{t: X_t \in D\}$, then $L < \infty$ almost surely. (By convention the supremum of the empty set is zero and the infimum of the empty set is infinity.) As

Received March 25, 1976.

¹ Supported in part by NSF Grant GP 41710.

² Supported in part by NSF Grant MPS 73-04961 A01.

AMS 1970 subject classifications. Primary 60J25, 60J45, 60J65.

Key words and phrases. Condenser potential, balayage, Hunt processes, capacitary measure, subprocesses.

usual $T_D = \inf \{t > 0 : X_t \in D\}$ denotes the hitting time of D . Let

$$(2.1) \quad \begin{aligned} \varphi(x) &= P_D 1(x) = P^x(T_D < \infty) = P^x(L > 0), \\ p(x) &= P^x(T_D < T_B). \end{aligned}$$

Then φ is an excessive function, while p is excessive relative to (X, T_B) . See Section III-5 of [2]. The operators P_D and P_B are the usual balayage or hitting operators. An inclusion-exclusion argument leads to the following formula

$$p = P^*(T_D < T_B) = P_D 1 - P_B P_D 1 + P_D P_B P_D 1 - \dots$$

The next proposition makes this precise. (C. Nevison informed us that he used it in a prior discussion.)

(2.2) PROPOSITION. *Let $p_n = (P_D P_B)^n P_D 1 = (P_D P_B)^n \varphi$. Then*

$$p = \sum_{n=0}^{\infty} (p_n - P_B p_n).$$

PROOF. Each p_n is excessive, bounded by one, and $P_B p_n \leq p_n$. Therefore $0 \leq p_n - P_B p_n \leq 1$. Let $T_0 = 0$, $T_1 = T_D$, $T_2 = T_D + T_B \circ \theta_{T_D}$, \dots , $T_{2n+1} = T_{2n} + T_D \circ \theta_{T_{2n}}$, $T_{2n+2} = T_{2n+1} + T_B \circ \theta_{T_{2n+1}}$. Thus T_1, T_2, T_3, \dots are the times of the successive visits to D , then to B , then back to D , and so on. A simple induction shows that $P_{T_{2n}} = (P_D P_B)^n$ for each $n \geq 0$. It is straightforward to check that

$$P^x\{T_{2n+1} \leq L \leq T_{2n+2}; T_D < T_B\} = p_n(x) - P_B p_n(x)$$

because L must lie in one of the intervals $[T_{2n+1}, T_{2n+2}]$. Note that the quasi-left-continuity of X implies that $\lim_n T_n = \infty$. This completes the proof of (2.2).

If $\sum p_n$ converges, then (2.2) may be written in the more agreeable form

$$(2.3) \quad p = \sum p_n - \sum P_B p_n.$$

We shall give some simple conditions that guarantee the convergence of $\sum p_n$. The hypotheses on D and B in the first paragraph of this section are still in force.

(2.4) PROPOSITION. *Suppose there exists a nearly Borel set G with $D \subset G \subset B^c$ and satisfying:*

- (i) $\sup \{U(x, G) : x \in E\} = M < \infty$.
- (ii) *There exist $t_0 > 0$ and $\eta > 0$ such that $P^x(T_{G^c} \geq t_0) \geq \eta$ for all $x \in \bar{D}^f$ —the fine closure of D .*

Then $\sum p_n(x)$ is bounded in x .

PROOF. Let (T_n) be the sequence defined in the proof of Proposition 2.2. Then

$$p_n(x) = P_{T_{2n}} \varphi(x) = P_{T_{2n}} P_D 1(x) = P^x(T_{2n+1} < \infty)$$

for each $n \geq 0$. Since $L < \infty$ and $T_n \uparrow \infty$ it is obvious that

$$P^x(T_{2n+1} < \infty \text{ for all } n) = 0.$$

Thus (2.4) is a matter of strenghtening this trivial fact to

$$\sup \sum_n P^x(T_{2n+1} < \infty) < \infty.$$

If $y \in \bar{D}^f$, then by (ii)

$$E^y \int_0^{T_{G^c}} 1_G(X_t) dt \geq \eta t_0.$$

Now using (i) we have

$$\begin{aligned} M &\geq U(x, G) \geq \sum_{n=0}^{\infty} E^x \int_{T_{2n+1}}^{T_{2n+2}} 1_G(X_t) dt \\ &= \sum_{n=0}^{\infty} E^x \{E^{X(T_{2n+1})} \int_0^{T_B} 1_G(X_t) dt\}. \end{aligned}$$

But $T_B \geq T_{G^c}$ and $X(T_{2n+1}) \in \bar{D}^f$ if $T_{2n+1} < \infty$. Therefore

$$M \geq \eta t_0 \sum_{n=0}^{\infty} P^x(T_{2n+1} < \infty),$$

establishing (2.4).

REMARKS. In (2.4ii) one need only assume that $g(x) = P^x(T_{G^c} \geq t_0) \geq \eta$ for $x \in D$ because it is immediate from (II-4.14) of [2] that g is finely continuous. If in (2.4i) one only assumes that $U(x, G)$ is finite for each x , then the proof shows that $\sum p_n(x)$ is finite for each x .

We next formulate a simple condition under which the hypotheses of (2.4) hold. The basic result that we need is a "separation" lemma that holds when the semigroup (P_t) maps C_0 into C_0 . Here C_0 is the space of continuous functions on E that vanish at infinity. This result is well known and may be found in [1], for example. Nevertheless we shall give the simple proof for the convenience of the reader.

(2.5) LEMMA. Let (P_t) map C_0 into C_0 . Let K be compact and let G be an open neighborhood of K . Then for each $\delta > 0$ there exists a $t_0 > 0$ such that

$$(2.6) \quad \inf_{x \in K} P^x(T_{G^c} \geq t_0) \geq 1 - \delta.$$

PROOF. We may assume without loss of generality that G has compact closure. For typographical convenience let $T = T_{G^c}$ during this proof. Since (P_t) maps C_0 into C_0 and $P_t f \rightarrow f$ pointwise as $t \rightarrow 0$ for each $f \in C_0$, it follows that, in fact, $\|P_t f - f\| \rightarrow 0$ as $t \rightarrow 0$ for each $f \in C_0$ where $\|\cdot\|$ is the usual supremum norm. See, for example, II-(2.15) of [2]. Choose $f \in C_0$ with $0 \leq f \leq 1$, $f = 1$ on K , and $f = 0$ on G^c . Given $\delta > 0$ there exists $t_0 > 0$ such that $\|P_t f - f\| < \delta/2$ for all $t \leq t_0$. Therefore

$$(2.7) \quad \sup_{t \leq t_0} \sup_{x \notin G} P_t f(x) < \delta/2$$

$$(2.8) \quad \inf_{t \leq t_0} \inf_{x \in K} P_t f(x) > 1 - \delta/2.$$

Thus if $x \in K$

$$(2.9) \quad 1 - \delta/2 < E^x[f \circ X_{t_0}] \leq P^x[T \geq t_0] + E^x[f \circ X_{t_0}; T < t_0],$$

and the strong Markov property implies

$$E^x[f \circ X_{t_0}; T < t_0] = E^x\{E^{X(T)}[f \circ X_{(t_0-T)^+}]; T < t_0\}.$$

But $X(T) \in G^c$ if $T < \infty$ and so by (2.7) this last expectation does not exceed $\delta/2$. Combining this with (2.9) yields

$$1 - \delta/2 \leq \inf_{x \in K} P^x(T \geq t_0) + \delta/2,$$

completing the proof of (2.5).

The following corollary is an immediate consequence of (2.4) and (2.5). Here, of course, B and D satisfy the conditions in the first paragraph of this section.

(2.10) COROLLARY. *Let (P_i) map C_0 into C_0 and assume that X is transient in the sense that $x \rightarrow u(x, K)$ is bounded for each compact K . Then if D has compact closure $\sum p_n(x)$ is bounded in x and*

$$p = \sum p_n - \sum P_B p_n .$$

3. In this section we shall assume that X satisfies the duality assumptions in Section VI-1 of [2] and the mild transience condition that there exists a sequence (h_n) of nonnegative functions with $h_n \uparrow 1$ and Uh_n finite for each n . Then for each x the potential kernel $u(x, y)$ is finite almost everywhere in y . See Section VI-1 of [2] for notation and terminology. As in the previous sections B and D are nearly Borel sets with disjoint closures with $L_D < \infty$. In addition throughout this section we shall suppose that the capacitary measure π_D of D exists; that is, π_D is the unique measure carried by \bar{D} satisfying $\varphi = P_D 1 = U\pi_D$. For example, if \bar{D} is compact and X satisfies conditions (VI-2.1), (VI-2.2), (VI-4.1), and (VI-4.2) of [2], then π_D exists. (See (VI-4.3) of [2].) However, much weaker conditions suffice. See [3] or [6] in this connection.

Let $v(x, y)$ be the potential kernel for (X, T_B) —the process X killed when it first hits B . Then v is positive kernel satisfying

$$(3.1) \quad \begin{aligned} u(x, y) &= v(x, y) + P_B u(x, y) \\ &= v(x, y) + u\hat{P}_B(x, y) . \end{aligned}$$

See [4], for example. As usual, write $V\mu(x) = \int v(x, y)\mu(dy)$ when μ is a positive measure. Let $\mu_n = \sum_{k \leq n} (\hat{P}_D \hat{P}_B)^k \pi_D$, and

$$(3.2) \quad \mu_D = \lim_n \mu_n = \sum_{k=0}^{\infty} (\hat{P}_D \hat{P}_B)^k \pi_D .$$

Then μ_D is a positive measure carried by \bar{D} since each μ_n is carried by \bar{D} . Of course, a priori, μ_D need not have any reasonable finiteness properties. However, V is a positive kernel and so

$$V\mu_D(x) = \lim V\mu_n(x)$$

exists. The fundamental identity for dual processes, VI-(1.16) of [2], yields

$$(3.3) \quad U\mu_n = \sum_{k=0}^n U(\hat{P}_D \hat{P}_B)^k \pi_D = \sum_{k=0}^n (P_D P_B)^k U\pi_D = \sum_{k=0}^n p_k .$$

Consequently $U\mu_n$ and $P_B U\mu_n$ are bounded for each n , and so using (2.2) and (3.1)

$$(3.1) \quad \begin{aligned} V\mu_D &= \lim_n V\mu_n = \lim_n (U\mu_n - P_B U\mu_n) \\ &= \lim_n \sum_{k=0}^n (p_k - P_B p_k) = p . \end{aligned}$$

Therefore

$$(3.4) \quad P^*(T_D < T_B) = p(x) = V\mu_D(x) ;$$

that is, μ_D as defined in (3.2) is the capacitary measure of D relative to the process (X, T_B) .

Next suppose that $\sum p_k$ is bounded, or only finite, for each x . Conditions guaranteeing this are given in (2.4) and (2.10). Then from (3.3), $U\mu_D = \sum_{k \geq 0} p_k$ is finite and so (3.4) may be written

$$p = V\mu_D = U\mu_D - P_B U\mu_D = U\mu_D - U\hat{P}_B \mu_D = U(\mu_D - \hat{P}_B \mu_D).$$

If we define $\nu = \mu_D - \hat{P}_B \mu_D$, then ν is a signed measure such that $U\nu(x) = p(x) = P^x(T_D < T_B)$. Therefore $U\nu = 1$ on D^r —the regular points of D —and 0 on B^r . But \bar{D} and \bar{B} are disjoint, and so $\nu^+ = \mu_D$ is carried by \bar{D} , more precisely by $D \cup {}^rD$ where rD is the set of coregular points of D , while $\nu^- = \hat{P}_B \mu_D$ is carried by \bar{B} , more precisely by $B \cup {}^rB$. In other words ν is the “condenser charge” for D and B and the formula

$$(3.5) \quad \nu = \mu_D - \hat{P}_B \mu_D$$

says that ν^+ is the capacitary measure μ_D of D relative to (X, T_B) and that ν^- is the balayage of $\nu^+ = \mu_D$ on B .

REMARKS. Of course, using the methods of Revuz [6], one can establish the existence of a measure μ_D such that $p = V\mu_D$ under duality and mild transience hypotheses. Then it is immediate that

$$(3.6) \quad U\mu_D = V\mu_D + P_B U\mu_D = p + U\hat{P}_B \mu_D.$$

But an additional “finiteness” argument seems to be necessary in order to conclude from (3.6) that

$$p = U\mu_D - U\hat{P}_B \mu_D = U(\mu_D - \hat{P}_B \mu_D).$$

Our approach shows that whenever π_D exists, then μ_D exists and is given by (3.2).

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