

14 Nov. 1984

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Dear Joan,

Heres' a quick summary of my thoughts so far on this bridge^{plat} thing.

Set, for each odd n , $p_n = e_1 e_3 e_5 \dots e_n \in A_n$

(A_n as in, say, my ~~index~~ Brauer groups, Hecke algs. paper)

Fact: p_n is a minimal projection in A_n , i.e.

~~p_n~~ $p_n A_n p_n \subseteq \mathbb{C} p_n$ - proof by induction.
(see JB - last page)

Fact: this means p_n "lives" in one of the simple ~~comp~~ summands of A_n . In fact it's the one on the extreme left of the Bratteli diagram. This is easily proved since this is the only one that gives the right trace.

Corollary. If $\alpha \in B_4$ $\wedge$ $\pi(\alpha) \in A_3$ in obvious way, then $e_1 e_3 \pi(\alpha) = e_1 e_3 \pi(\alpha')$ α' being the image of α under the homomorphism from B_4 to B_3 .
the α' is obtained by deleting the factor e_4 from α , i.e. $\alpha' = \alpha e_4^{-1}$

Corollary (2) $e_1 e_3 (g_2 g_1 g_3 g_2^{-1}) = e_1 e_3$

Definition define $R: A_n \rightarrow \mathbb{C}$ by $p_n \alpha p_n = R(\alpha) p_n$

Proposition (i) R is well defined on $\bigcup_{n=1}^{\infty} A_n$

(ii) $R(\alpha) = \frac{1}{\frac{n+1}{2}} \text{tr}(p_n \alpha)$

(both trivial) Proof of (ii)

there it is ok to omit the factor e_4 because $e_1 e_3$ commutes with the generator of $\ker(B_4 \rightarrow B_3)$, so if $x \in \ker$ we have $(e_1 e_3)x = (e_1 e_3)^2 x = (e_1 e_3)x(e_1 e_3)$.
Corollary 2 is true for all $x \in \ker$, however since the kernel is generated by $g_2 g_1 g_3 g_2^{-1}$ and $g_1 g_2^{-1}$ this is the only non-trivial case.

Now define a function on $B_{n+1} \rightarrow$ ^{Laurent} n polys. in t by (2)

$$J_\alpha(t) = (-t+1)^{\frac{n+1}{2}} R(\pi(\alpha))$$

$\left(\frac{-(t+1)}{\sqrt{t}} \right)^{\frac{n+1}{2}}$ See p 5
but these are the same mod t^k

Theorem If the plat $\tilde{\alpha}$ associated with α is a knot then

$$V_{\tilde{\alpha}}(t) = t^{\text{some power}} J_\alpha(t)$$

Proof First let's see how J_α varies on double cosets of the group K gen. by

(i) odd g_i 's

(ii) $\sigma_{2k} \sigma_{2k-1} \sigma_{2k+1} \sigma_{2k}$

(iii) $\sigma_{2k} \sigma_{2k-1} \sigma_{2k+1}^{-1} \sigma_{2k}^{-1}$ due to algebra for B_n

i) Remember $g_i e_i = t e_i$ so if i is odd $p_n g_i = e e_3 \dots e_n$

$$p_n \pi(\alpha) p_n = R(\pi(\alpha) g_i) p_n = p_n \pi(\alpha) g_i p_n = t R(\pi(\alpha)) p_n$$

(ii) ~~The~~ Almost all the e_i 's in p are irrelevant so it suffices to do the computation: $e_1 e_3 g_2 g_1 g_3 g_2 e_1 e_3$
and I claim $(e_1 e_3 g_2 g_1 g_3 g_2 = t e_1 e_3$

first of all as you know $(g_2 g_1 g_3 g_2) g_1 (g_2 g_1 g_3 g_2)^{-1} = g_3$ & same $3 \rightarrow 1$

so the same is true of the e 's and $g_2 g_1 g_3 g_2$ commutes with $e_1 e_3$ so

$$e_1 e_3 g_2 g_1 g_3 g_2 = (e_1 e_3 g_2 g_1 g_3 g_2) e_1 e_3 = \text{const. } e_1 e_3$$

because $p_n \pi(\alpha) p_n = R(\alpha) p_n \neq \alpha \in B_{n+1}$

just have to compute the constant

✓ it's easy to see that it's just $\frac{1}{t^2} \text{tr}(e_1 e_3 g_2 g_1 g_3 g_2)$ and by the Proposition (ii) on bottom of page 1

by ^{1st} ~~remark~~ corollary, this is $\frac{1}{t} \text{tr}(e_1 e_3 g_2 g_1^2 g_2) = e_1 e_3 (g_2 g_1^2 g_2)$ ^{become $e_1 e_3 (g_2 g_1 g_2 g_1) = e_1 e_3 (g_2 g_1 g_2^{-1} g_1) (g_2 g_1^2 g_2)$} 3

$$= \frac{1}{t} \text{tr}(e_1 g_2 g_1^2 g_2)$$

now $g_1^2 = (t-1)g_1 + t$ so

$$= \frac{t-1}{t} \text{tr}(e_1 g_2 g_1 g_2) + \frac{t}{t} \text{tr}(e_1 g_2^2)$$

$$= \frac{t-1}{t} \text{tr}(e_1 g_1 g_2 g_1) + \frac{t}{t} \text{tr}(g_2^2)$$

$$= \frac{(t-1)t^2}{t} \text{tr}(g_2) + t \text{tr}(g_2^2)$$

now $g_2^2 = (t^2-1)e_2 + 1$ so $\text{tr}(g_2^2) = \frac{(t^2-1)t}{(1+t)^2} + 1 = \frac{t^2-t+1+t}{1+t}$

$$= (t-1)t^2 \left(\frac{-1}{1+t} \right) + t \cdot \frac{t^3+t^2}{1+t} = \frac{t^2+t}{1+t} = t$$

(there may be a much more elegant way to do this)

$$\text{thus } g_2 g_1 g_2 e_1 e_3 = e_1 e_3 g_2 g_1 g_2 = t e_1 e_3$$

(iii) follows from lemma (d) that $g_{2k} g_{2k+1} g_{2k+1}^{-1} g_{2k}^{-1} p_i = p_i$

Thus we see that if $x, y \in K$

$$J_{x \otimes y} = t^{\text{same power}} J_x$$

Now let's look at stabilization: $R(x) = \frac{1}{t^{n+1}} \text{tr}(e_1 e_3 \dots e_n x)$

If $x \in A_n$, n odd then $R(x g_{n+1}) = \frac{-1}{(t+1)} R(x)$
 the claim $R(x g_{n+1}^{-1}) = \frac{-t}{1+t} R(x)$

Proof $R(x g_{n+1}) = \frac{1}{t^{n+3}} \text{tr}(p_{n+2} x) \stackrel{g_{n+1}}{=} \frac{1}{t^{n+3}} \text{tr}(e_1 e_3 \dots e_n e_{n+2} x g_{n+1}) =$
 similarly for g_{n+1}^{-1} $\frac{1}{t^{n+3}} \text{tr}(p_{n+2} x) \stackrel{g_{n+1}^{-1}}{=} \frac{1}{t^{n+3}} \text{tr}(e_1 e_3 \dots e_n e_{n+2} x g_{n+1}^{-1}) = \frac{-1}{1+t} R(x)$ only occurring e_{n+2} and e_{n+1}

$$\alpha \in B_{n+1}$$

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Thus $\nearrow$

$$\begin{aligned} J_{\alpha \sigma_{n+1}} &= \left(-(t+1) \right)^{\frac{n+3}{2}} R(\pi(\alpha \sigma_{n+1})) \\ &= \left(-(t+1) \right)^{\frac{n+3}{2}} \cdot \frac{-1}{(t+1)} R(\pi(\alpha)) \\ &= \left(-(t+1) \right)^{\frac{n+1}{2}} R(\pi(\alpha)) \\ &= \bar{J}_{\alpha} \end{aligned}$$

$$e J_{\alpha \sigma_{n+1}^{-1}} = t J_{\alpha}$$

by your theorem

We see that $\bar{J}_{\alpha}$ depends, up to powers of t , only on $\tilde{\alpha}$.
We now want to compute it for a specific isotoped $\tilde{\alpha}$, i.e. a closed braid representation $\beta \in B_m$, some m , with $\hat{\beta} = \tilde{\alpha}$.

As you know, if $\sigma = \sigma_2 \sigma_3 \dots \sigma_{2m-1} \sigma_3 \sigma_4 \dots \sigma_{2m-2} \dots \sigma_m \sigma_{m+1}$,
 $\tilde{\alpha} = \sigma \sigma^{-1} = \hat{\beta}$. The following you also must know.

$$\sigma \sigma_1 \sigma^{-1} = \sigma_1^{-1} \sigma_2 \sigma_1, \quad \sigma \sigma_2 \sigma^{-1} = \sigma_3^{-1} \sigma_4 \sigma_3, \quad \dots \quad \sigma \sigma_{m-1} \sigma^{-1} = \sigma_{2m-3}^{-1} \sigma_{2m-2} \sigma_{2m-3}$$

This means $\sigma \sigma_i \sigma^{-1} = \sigma_i^{-1} \sigma_{i+1} \sigma_i$ etc.

Now I claim that if $\varphi: UA_n \rightarrow \mathbb{C}$ is any linear functional with $\varphi(1) = 1$, $\varphi(x e_{n+1} y) = \tilde{\varphi} \varphi(xy)$, $x, y \in A_n$, then $\varphi = \text{tr}$.
This is easy by induction and reduced words on the e_i 's.
So I claim that φ defined by $\varphi(x) = \frac{1}{\tilde{\varphi}(n)} \text{tr}(e_1 e_3 \dots e_{2n-1} \sigma x \sigma^{-1})$
is such a linear functional. $\underline{\underline{x \in A_n}}$

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By induction on n . First of all, well definedness is trivial ~~from $\sigma e_i \sigma^{-1}$ formula~~ (i.e. φ is defined on VA_n) so we may use induction on n , trivial for A_1

$$\begin{aligned}\varphi(\alpha e_{n+1} y) &= \frac{1}{t^{n+1}} \text{tr}(e_1 e_3 \dots e_{2n-1} e_{2n+1} \sigma x \sigma^{-1} \sigma_{2n+1}^{-1} e_{2n+2} \sigma_{2n+1} \sigma y \sigma^{-1}) \\ &= \frac{1}{t^n} \text{tr}(e_1 e_3 \dots e_{2n-1} e_{2n+1} \sigma x y \sigma^{-1}) \\ &= \tau \left(\frac{1}{t^n} \text{tr}(e_1 e_3 \dots e_{2n-1} \sigma x y \sigma^{-1}) \right)\end{aligned}$$

(note $\sigma x y \sigma^{-1} \sigma x \sigma^{-1}, \sigma y \sigma^{-1} \in A_{2n}$)

$$= \tau \varphi(\alpha y)$$

Thus $\varphi = \text{tr}$ and if $\beta \in B_m$

$$\begin{aligned}V_{\beta}(t) \varphi(\alpha) &= \left(\frac{t+1}{\sqrt{t}} \right)^{m-1} \text{tr}(\pi(\beta)) \\ &= \left(\frac{t+1}{\sqrt{t}} \right)^{m-1} \varphi(\pi(\beta)) \\ &= \left(\frac{t+1}{\sqrt{t}} \right)^{m-1} \frac{1}{t^{m-1}} \text{tr}(e_1 e_3 \dots e_{2m-3} \pi(\sigma \beta \sigma^{-1})) \\ &= \left(\frac{t+1}{\sqrt{t}} \right)^{m-1} \frac{1}{t^{m-1}} \text{tr}(P_{2m-3} \pi(\sigma \beta \sigma^{-1})) \\ &= \left(\frac{t+1}{\sqrt{t}} \right)^{m-1} R(\pi(\sigma \beta \sigma^{-1})) \\ &= \left(\frac{t+1}{\sqrt{t}} \right)^{m-1} (-t+1)^{-m+1} J(\sigma \beta \sigma^{-1}) \\ &= t^{\text{some power}} J(\alpha) \text{ since}\end{aligned}$$

" $n = 2m-3$ "
" $\frac{n+1}{2} = m-1$ "

$$\tilde{\alpha} \stackrel{\text{isotopy}}{=} \sigma \beta \sigma^{-1}$$

Q.E.D.

$$\alpha \in B_n$$

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Corollary If $\alpha \in \ker \pi$ for $t = e^{\frac{2\pi i}{k}}$ $k=4,5,\dots$

and $\tilde{\alpha}$ is a knot then

~~link~~ crookedness $(\tilde{\alpha}) = n$.

{Arveson
character to C^* algebras}

Proof $R(\alpha)$ is a "state" in C^* -sense, i.e.

$R(\alpha^* \alpha) \geq 0$ so we have Cauchy Schwarz,

$$|R(\alpha^* \beta)| \leq R(\alpha^* \alpha)^{\frac{1}{2}} R(\beta^* \beta)^{\frac{1}{2}}$$

in particular if u is unitary

$$|R(u)| \leq R(u^* u)^{\frac{1}{2}} R(1 \cdot 1)^{\frac{1}{2}} = 1$$

so that if $\beta \in B_m$, $m \leq n$

$$|J_{\beta}(e^{\frac{2\pi i}{k}})| \leq (2 \cos \frac{\pi}{k})^m$$

$$\text{But if } \alpha \in \ker \pi, |J_{\alpha}(e^{\frac{2\pi i}{k}})| = (2 \cos \frac{\pi}{k})^n > (2 \cos \frac{\pi}{k})^m$$

Q.E.D. for $m < n$

Corollary if $\alpha = \text{product of } \sigma_i$'s & GCD of exponents of $\alpha > 1$, then ~~link~~ crookedness $(\tilde{\alpha}) = n$.

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So far I've not been able to do anything better with it. But it still seems a miracle.

Nor do I see what to do with general rectangular Young tableaux, nor if their 2-variable version has such an interpretation.

Best wishes,

Vampham